

Fast Automatic Arc Detection

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Searching For Strong Lenses in Large Imaging Surveys

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- 1 Motivation
- 2 Arcfinder method
 - Partitioning into cells
 - Cell transport
 - Cell ellipticities
 - Cell correlation and object generation
 - Graph generation
- 3 Problems / future work
 - Problems: spurious detections
 - Future work
- 4 Results
 - HST / WFPC2

Employing visual inspection for arc searches is problematic:

- depends on intensity scaling
 - hidden faint arcs near bright objects possible
- ambiguous feature classification bad for statistics
- data volume increases rapidly with future surveys
- needs a priori information
 - selection effects
 - hides arcs near dark clusters

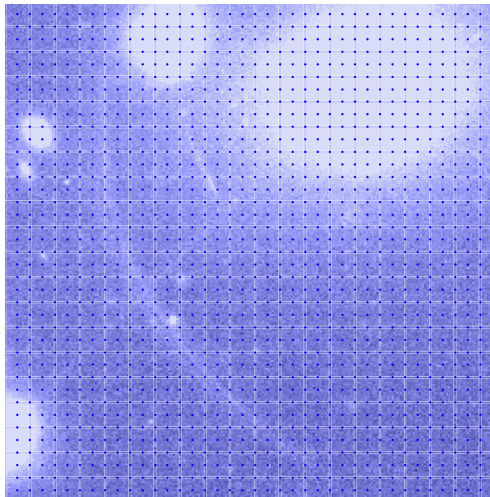
Fast, automated arc detection is desirable.

Partitioning into cells

- distribute cells on rectangular grid



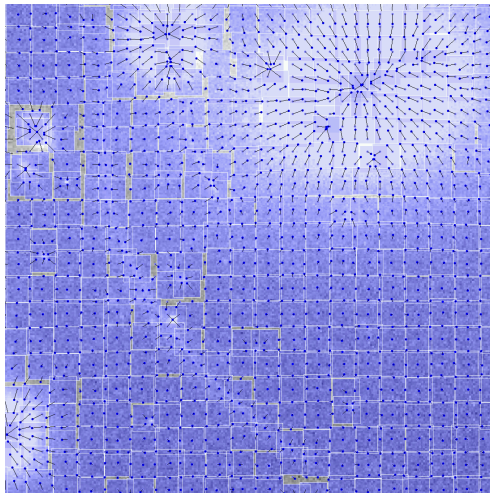
- distribute cells on rectangular grid



- distribute cells on rectangular grid
- shift to local centre-of-brightness

centre of brightness

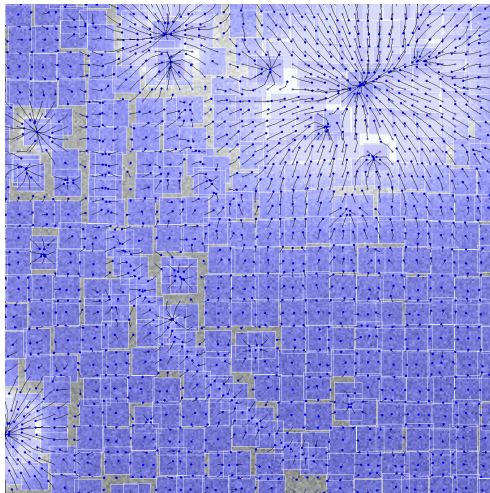
$$\vec{x} = \frac{\int_A \vec{x} q(I(\vec{x})) d^2x}{\int_A q(I(\vec{x})) d^2x}$$



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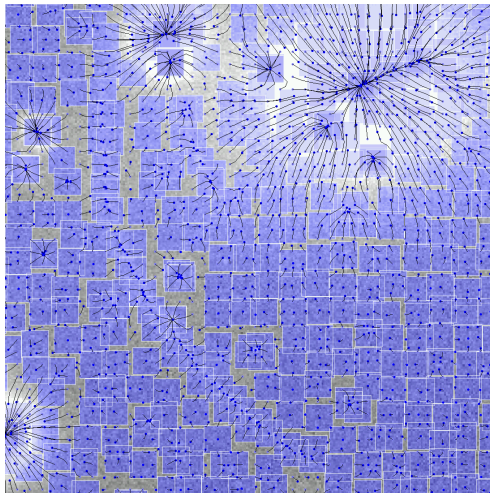
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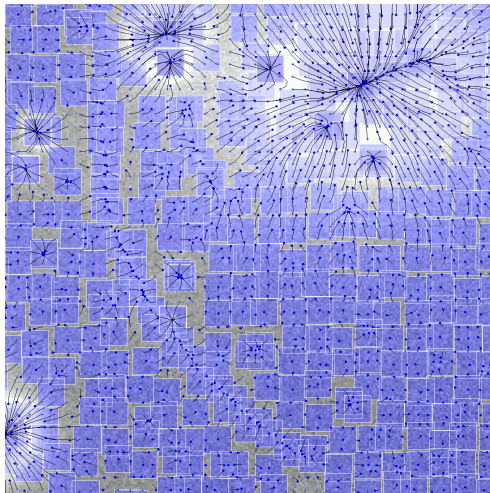
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- ellipticities
⇒ orientations

second-moments Q_{ij}

$$\frac{\int_A (x_i - \bar{x}_i)(x_j - \bar{x}_j) q(I(\vec{x})) d^2x}{\int_A q(I(\vec{x})) d^2x}$$

complex ellipticity χ

$$\chi = \frac{Q_{11} - Q_{22} + 2iQ_{12}}{Q_{11} + Q_{22}}$$



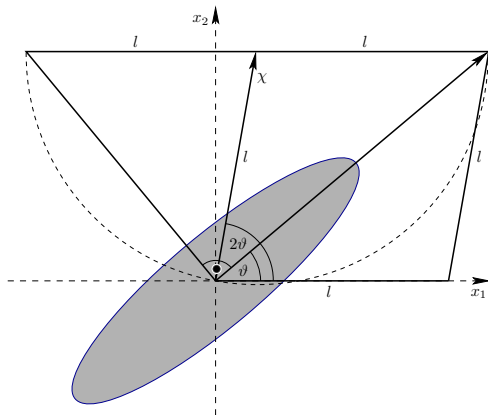
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$$\chi = \frac{(1-r^2)}{(1+r^2)} \exp(2i\vartheta)$$



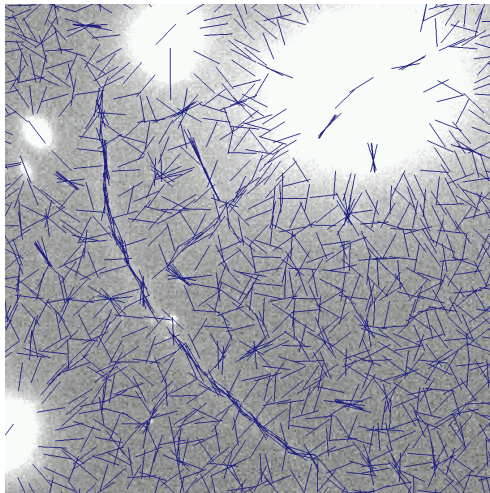
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- cell correlations c^i
- $c^i > c_{\text{thres}} \Rightarrow$ add cell i to an object

cell correlation

$$c^i = \frac{1}{|\mathcal{N}|} \sum_{j \in \mathcal{N}} c^{ij}$$

$$c^{ij} = c_d^{ij} c_x^{ij}$$

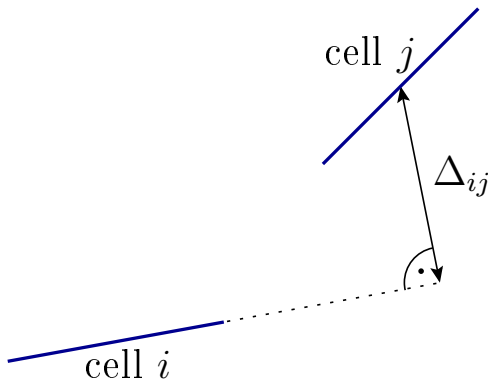
$$c_d^{ij} = |\vec{e}^i \vec{e}^j|$$

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\mathcal{N} : cell neighborhood

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d : initial separation



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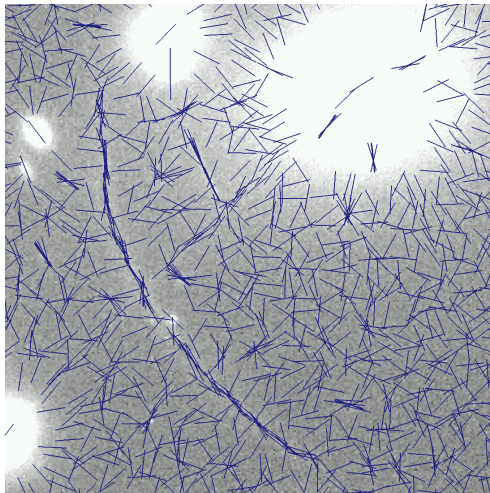
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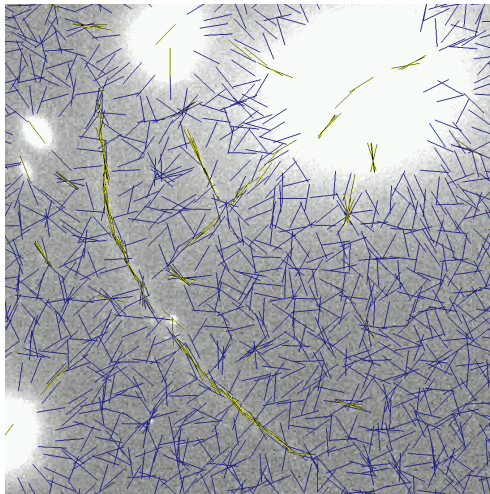
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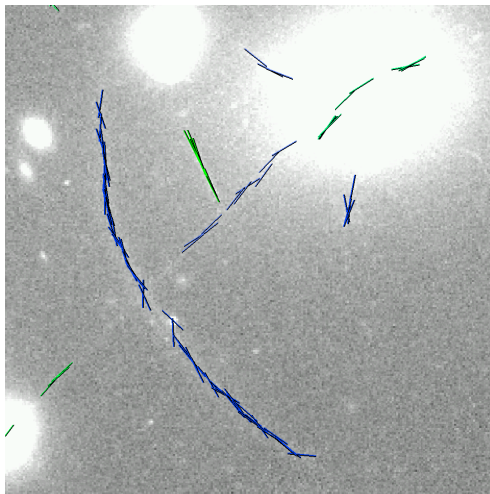
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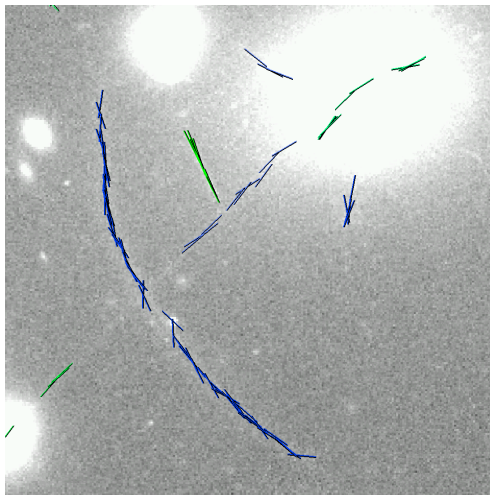
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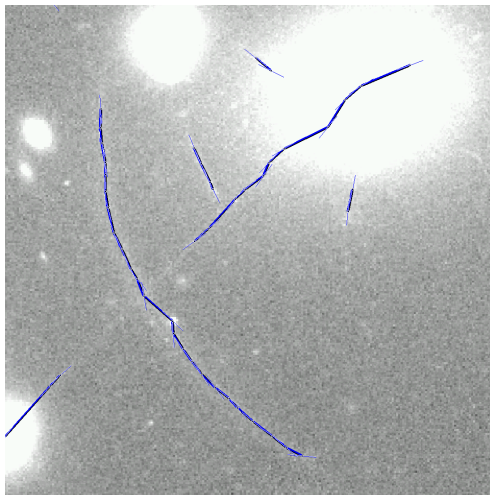
- basic object filter:
minimal cellcount
and diameter
- generate linear
graphs following
arc ridgeline



objects:

unsorted sets of cells

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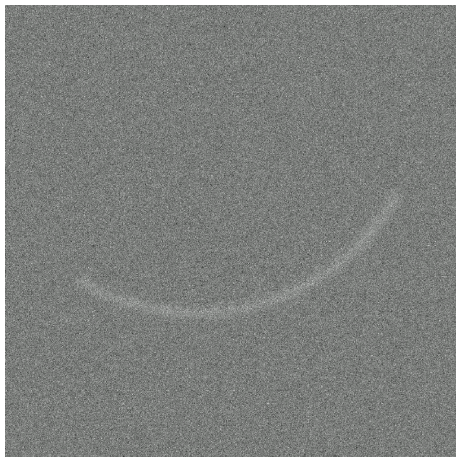


objects:

unsorted sets of cells

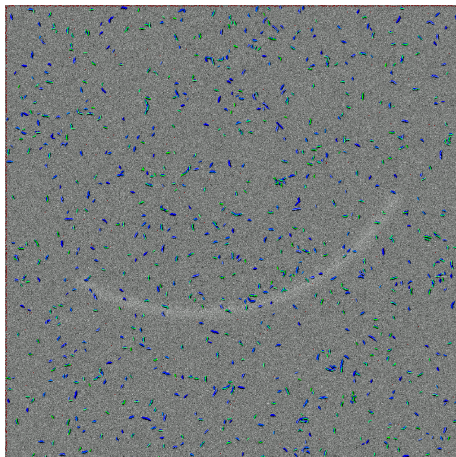
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation
- galaxies
- spikes and blooming
- point sources



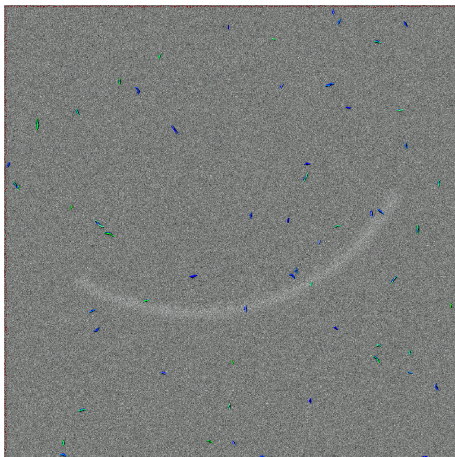
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation
scale size 5:
715 objects
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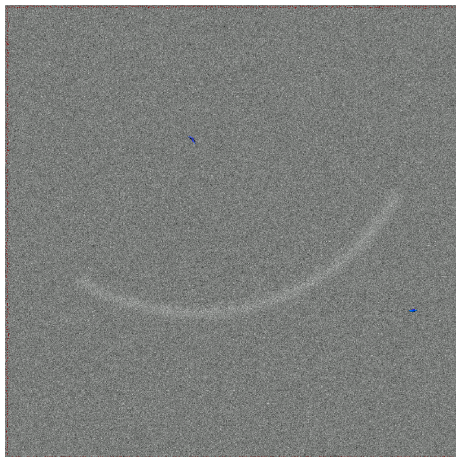
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation
scale size 7:
49 objects
- galaxies
- spikes and blooming
- point sources



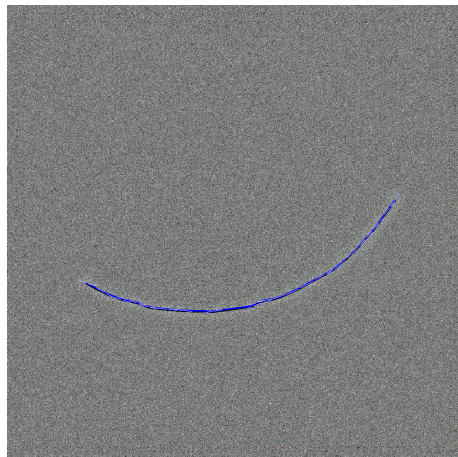
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation
scale size 9:
2 objects
- galaxies
- spikes and blooming
- point sources



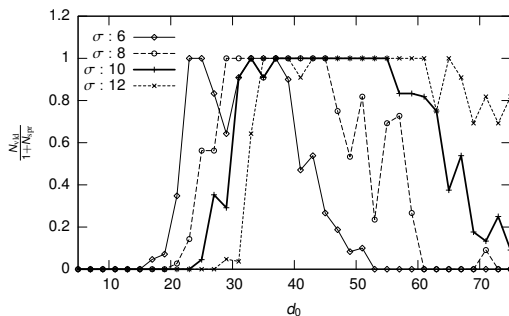
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation
scale size 39:
1 object
- galaxies
- spikes and blooming
- point sources



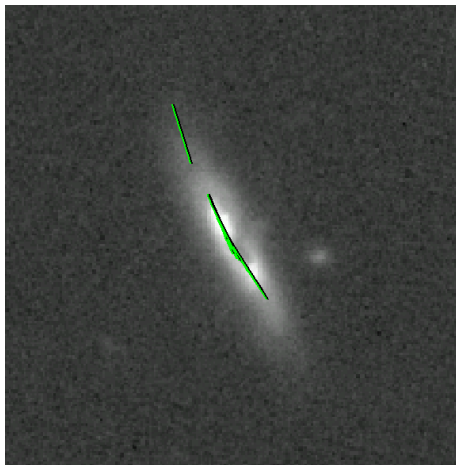
Spurious detections caused by several types of image features:

- Poissonian noise / pixel correlation scale $\mapsto \frac{\text{detections}}{\text{candidates}}$:
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- point sources



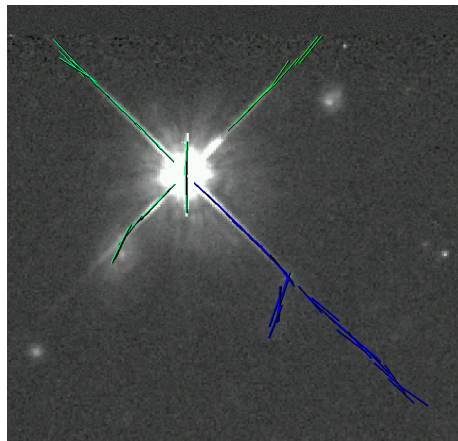
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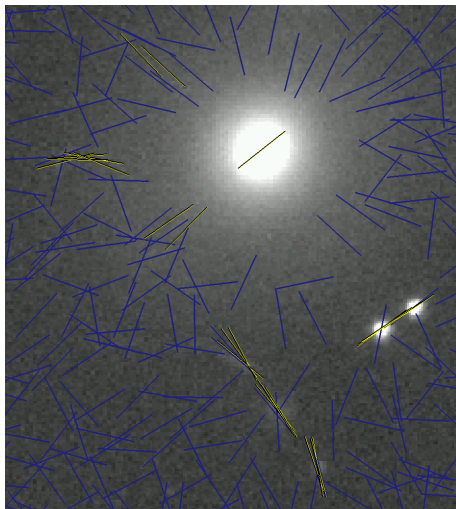
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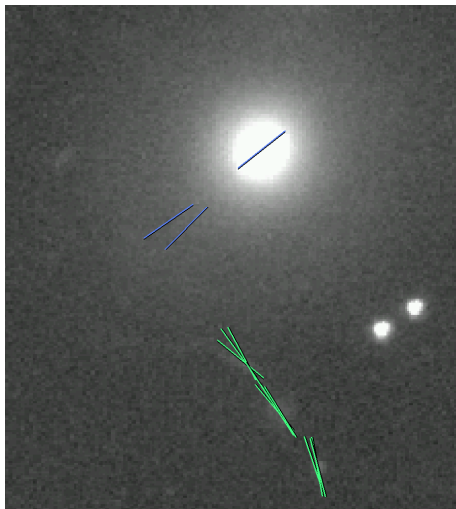
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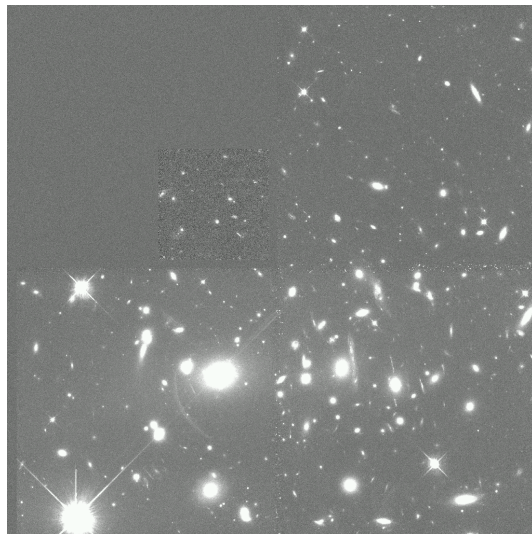
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- post processing to remove as many spurious detections as possible
- determination of detection efficiency using simulated images
- **application to datasets**

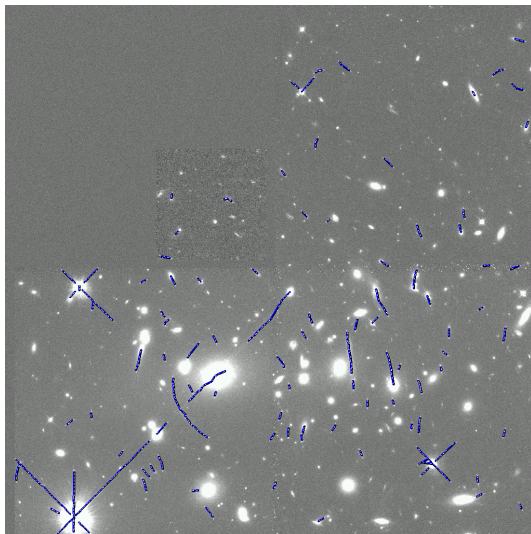
Abell2390 by HST WFPC2

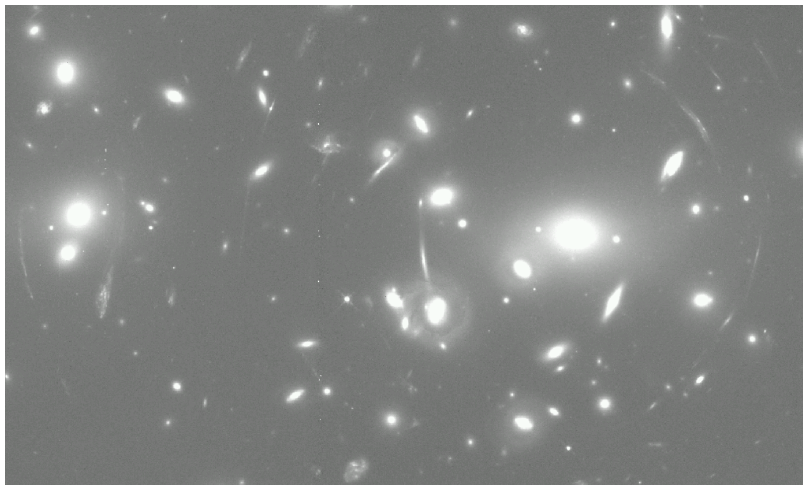
Processing time
approx. 2.7s on
2.26GHz CPU



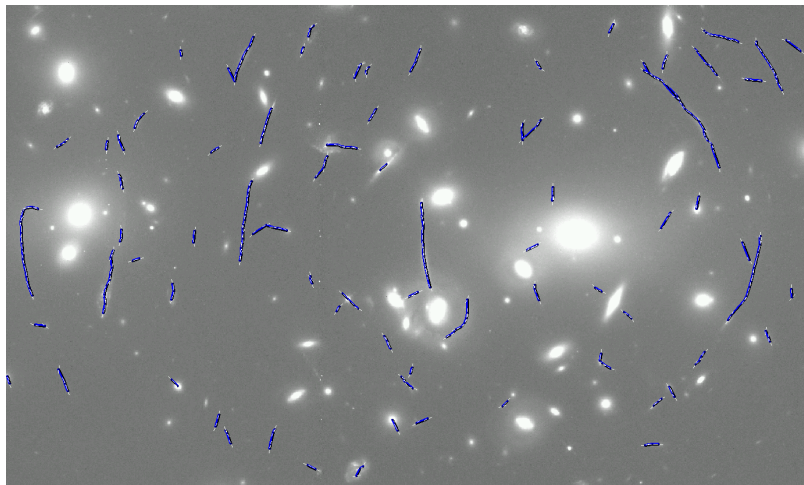
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HST WFPC2 image of Abell2218 with several detected arcs.
Also several false positives.



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